ECE 456 - Problem Set 3 (Part 1)

David Lenfesty

Phillip Kirwin

lenfesty@ualberta.ca

pkirwin@ualberta.ca

2021-03-31

Problem 1

(a) (i) The matrix equation is

$$[\hat{H}]\{\phi\} = E\{\phi\},\,$$

where $[\hat{H}]$ is an N-by-N matrix with $[\hat{H}]_{nm} = 0$ except for the following elements:

$$[\hat{H}]_{nn} = 2t_0 + U_n$$
$$[\hat{H}]_{n,n\pm 1} = -t_0$$
$$[\hat{H}]_{0,N} = [\hat{H}]_{N,0} = -t_0,$$

with $t_0 = \hbar^2/(2ma^2)$ and $U_n = U(na)$. The N-vector $\{\phi\}$ has elements ϕ_n which each represent the value of the eigenvector at the point $na = x_n$.

(ii) The expression of the wave function $\phi(x)$ as a sum of basis functions is as below:

$$\phi(x) = \sum_{n=1}^{N} \phi_n u_n(x)$$

The derived matrix equation:

$$[\hat{H}]_u\{\phi\} = [S]_u\{\phi\}$$

Where $[\hat{H}]_u$ is a matrix with the elements:

$$H_{nm} = \int u_n^*(x) \hat{H} u_m(x) dx$$

and $[S]_u$ is a matrix with the elements:

$$S_{nm} = \int u_n^*(x)u_m(x)dx$$

 $[\hat{H}]_u$ and $[S]_u$ are both of size N-by-N. The elements of $\{\phi\}$, ϕ_n , are the expansion coefficients of $\phi(x)$.

(b) (i) code:

The bonding and antibonding eigenenergies are $\boxed{-32.2567\,\mathrm{eV}}$ and $\boxed{-15.5978\,\mathrm{eV}}$ respectively.

(ii) Neglecting normalization, we have the following expressions for $\phi_B(z)$ and $\phi_A(z)$:

$$\phi_B(z) = u_L(z) + u_R(z)$$

$$\phi_A(z) = u_L(z) - u_R(z).$$

We obtain the following plot:

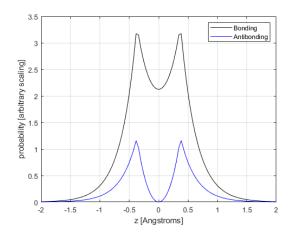


Figure 1. non-normalized probability densities for bonding and antibonding solutions.

Problem 2

(a) (i)

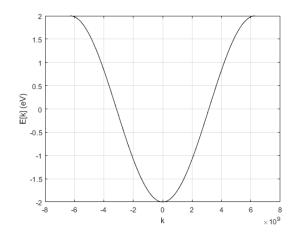


Figure 2. Energy vs. wave vector relationship.

- (ii) Energy values from -2 eV to 2 eV are allowed.
- (iii) The vector $\{\phi\}$, which is of length N, and has elements n is:

$$\{\phi\} = Ce^{ik \cdot na}$$

$$\{\phi\} = \begin{bmatrix} Ce^{ika} \\ Ce^{ik2a} \\ \vdots \\ C_Ae^{ikNa} \end{bmatrix}$$

The corresponding wave function is:

$$\phi(x) = \sum_{n=1}^{N} Ce^{ik \cdot na} u_n(x)$$

There is one wave function and thus one energy level for each value of k. This means that there is one electronic state per k.

(b) (i)

$$\{\phi\} = \begin{bmatrix} C_A e^{ika} \\ C_B e^{ika} \\ C_A e^{ik2a} \\ C_B e^{ik2a} \\ \vdots \\ C_A e^{ikNa} \\ C_B e^{ikNa} \end{bmatrix}$$

(ii)

$$\phi(x) = \sum_{n=1}^{N} C_A e^{ikna} u_{nA}(x) + C_B e^{ikna} u_{nB}(x)$$

(iii) [h(k)] is of size 2-by-2. Thus there will be two values of E(k) for a fixed k. This also means there are two $\phi(x)$ for each k.

(c) (i)

$$\begin{aligned} \phi_2 + 2\phi_3 + \phi_4 &= E\phi_1 \\ \phi_1 + \phi_3 + 2\phi_4 &= E\phi_2 \\ 2\phi_1 + \phi_2 + \phi_4 &= E\phi_3 \\ \phi_1 + 2\phi_2 + \phi_3 &= E\phi_4 \end{aligned}$$

(ii)

$$\phi_2 + 2\phi_3 + \phi_0 = E\phi_1$$

$$\phi_1 + \phi_3 + 2\phi_4 = E\phi_2$$

$$2\phi_5 + \phi_2 + \phi_4 = E\phi_3$$

$$\phi_5 + 2\phi_6 + \phi_3 = E\phi_4$$

(iii) A generalized form of the *n*th equation is:

$$E\phi_n = \phi_{n-1} + \phi_{n+1} + 2\phi_{n+2}$$

(iv)

$$ECe^{ikna} = Ce^{ik(n+1)a} + Ce^{ik(n-1)a} + 2Ce^{ik(n+2)a}$$

$$E = e^{ika} + e^{-ika} + 2e^{2ika}$$

$$E(k) = 2e^{2ika} + 2\cos(ka)$$
(1)

(v) Imposing the repeating boundary conditions $\phi_{n+4} = \phi_n$, We obtain the following relationship:

$$Ce^{ikna} = Ce^{ik(n+4)a}$$
$$1 = e^{i4ka}$$

For this to hold, 4ka must be some multiple of 2π , and this mean $k = \frac{\pi}{2a} \cdot integer$.

(vi) Using the E-k relationship from equation 1, we know that k must always be real, so the $2\cos(ka)$ portion of the E-k relationship must be real. As well, if we substitute in the equation for k we obtained in part (v), we get the following (partial) expression:

$$2e^{i2ka} = 2e^{i\pi \cdot integer}$$

Which we know will always be real (with a value of ± 2).

(vii) Since $e^{2\pi n} = 1$, we have:

$$\phi_n(k + \frac{2\pi}{a}) = Ce^{i(k + \frac{2\pi}{a}) \cdot nA} = Ce^{ik \cdot nA}$$
$$\phi_n(k + \frac{2\pi}{a}) = \phi_n(k).$$

Therefore wavefunctions for which k is separated by $\frac{2\pi}{a}$ are equivalent, and we only need consider the range $k \in [-\frac{\pi}{a}, \frac{\pi}{a}]$.

Problem 3

(a) Given the geometry and interaction rules stated, the interaction matrices $[H]_{nm}$ are zero except for

$$[H]_{nn} = \begin{bmatrix} E_0 & t_i \\ t_i & E_0 \end{bmatrix}$$
$$[H]_{n,m*} = \begin{bmatrix} t_A & 0 \\ 0 & t_B \end{bmatrix}$$

where m* corresponds to any of the four nearest neighbor square-shaped unit cells to cell n. For cell n, let cell a be above, cell b be to the right, cell c be below, and cell d be to the left. Given that each cell is spaced a length a apart, the associated phase factors for nonzero $H_{nm},\,e^{i\vec{k}\cdot(\vec{d_m}-\vec{d_n})},$ are then:

- (n): 1
- $(a): e^{ik_y a}$ $(b): e^{ik_x a}$ $(c): e^{-ik_y a}$

with $\vec{k} = k_x \hat{x} + k_y \hat{y}$. The Bloch matrix then follows:

$$\begin{split} [h(\vec{k})] &= \sum_{m} [H]_{nm} e^{i\vec{k} \cdot (\vec{d_m} - \vec{d_n})} \\ &= \begin{bmatrix} E_0 + t_A \left(e^{ik_x a} + e^{-ik_x a} + e^{ik_y a} + e^{-ik_y a} \right) & t_i \\ t_i & E_0 + t_B \left(e^{ik_x a} + e^{-ik_x a} + e^{ik_y a} + e^{-ik_y a} \right) \end{bmatrix} \\ &= \begin{bmatrix} E_0 + 2t_A \left(\cos(k_x a) + \cos(k_y a) \right) & t_i \\ t_i & E_0 + 2t_B \left(\cos(k_x a) + \cos(k_y a) \right) \end{bmatrix} \end{split}$$

To find the E- \vec{k} relationship in terms of cosine functions, we must first find h_0 in terms of trigonometric (b) functions. We will require the following trigonometric identities to do so:

$$\sin(\alpha \pm \beta) = \sin(\alpha)\cos(\beta) \pm \sin(\beta)\cos(\alpha) \tag{2}$$

$$\cos(\alpha \pm \beta) = \cos(\alpha)\cos(\beta) \mp \sin(\alpha)\sin(\alpha) \tag{3}$$

$$1 = \sin^2(\theta)\cos^2(\theta),\tag{4}$$

as well as the following general sine/cosine properties:

$$\cos(\theta) = \cos(-\theta)$$

$$\sin(\theta) = -\sin(-\theta).$$
(5)

First we can rewrite the exponentials in h_0 using Euler's identity:

$$h_0 = -t_c \left(1 + \cos(-k_x a - k_y b) + i \sin(-k_x a - k_y b) + \cos(-k_x a + k_y b) + i \sin(-k_x a + k_y b) \right)$$

Using identities (2) and (3), we can expand this relationship further.

$$h_0 = -t + c(1 + \cos(-k_x a)\cos(-k_y b) - \sin(-k_x a)\sin(-k_y b) + i\sin(-k_x a)\cos(-k_y b) + i\sin(-k_y b)\cos(-k_x a) + \cos(k_y b)\cos(k_x a) + \sin(k_y b)\sin(k_x a) + i\sin(k_y b)\cos(k_x a) - i\sin(k_x a)\cos(k_y b))$$

Here we can use the properties from (5) to reduce this equation. Since $|h_0|^2 = h_0 h_0^*$, we also obtain a simple expression for h_0^* .

$$h_0 = -t_c (1 + 2\cos(k_x a)\cos(k_y b) - 2i\sin(k_x a)\cos(k_y b))$$

$$h_0^* = -t_c (1 + 2\cos(k_x a)\cos(k_y b) + 2i\sin(k_x a)\cos(k_y b))$$

We can now find $|h_0|^2 = h_0 h_0^*$:

$$h_0 h_0^* = 1 + 4\cos(k_x a)\cos(k_y b) + 4\cos^2(k_y b)$$

From this, we can finally obtain an expression for $E(\vec{k})$:

$$E(\vec{k}) = E_0 \pm t_c \sqrt{1 + 4\cos(k_x a)\cos(k_y b) 4\cos^2(k_y b)}$$
(6)

Problem 4

(a) We can substitute (from the assignment) equation (24) into equation (23):

$$\sum_{k} i\hbar \frac{\delta}{\delta t} c_k(t) \phi_k(x) e^{-i[E(k)/\hbar]t} = \sum_{k} c_k(t) \hat{H}_0 \phi(x) e^{-i[E(k)/\hbar]t}$$
(7)

$$+\sum_{k} c_k(t) U_s(x,t) \phi_k(x) e^{-i[E(k)/\hbar]t}$$
(8)

We can partially evaluate the derivative on the left hand side:

$$\frac{\delta}{\delta t} c_k(t) \phi_k(t) e^{-i[E(k)/\hbar]t} = \frac{\delta c_k(t)}{\delta t} \phi_k(t) e^{-i[E(k)/\hbar]t} - \frac{i}{\hbar} c_k(t) E(k) \phi_k(x) e^{-i[E(k)/\hbar]t}$$

Expanding the rightmost term out into the summation, we get the expression $\sum_k c_k(t) E(k) \phi_k(x) e^{-i[E(k)/\hbar]t}$. Since $\hat{H}_0 \phi_k(x) = E(k) \phi_k(x)$, we can see that this cancels out the term with \hat{H}_0 in our first substition (8), and we get the final differential equation:

$$\sum_{k} c_k(t) U_s(x,t) \phi_k(x) e^{-i[E(k)/\hbar]t} = \sum_{k} i\hbar \frac{\delta c_k(t)}{\delta t} \phi_k(x) e^{-i[E(k)/\hbar]t}$$

(b)

$$\begin{split} \sum_k c_k(t) \left[\int \phi_{k_f}^*(x) U_s(x,t) \phi_k(x) \, dx \right] e^{-i[E(k)/\hbar]t} &= \sum_k i\hbar \frac{\partial c_k(t)}{\partial t} \left[\int \phi_{k_f}^*(x) \phi_k(x) \, dx \right] e^{-i[E(k)/\hbar]t} \\ & \sum_k c_k(t) I_{k_f k} e^{-i[E(k)/\hbar]t} &= \sum_k i\hbar \frac{\partial c_k(t)}{\partial t} \delta_{k_f k} e^{-i[E(k)/\hbar]t} \\ & \sum_k c_k(t) I_{k_f k} e^{-i[E(k)/\hbar]t} &= i\hbar \frac{\partial c_k(t)}{\partial t} e^{-i[E(k)/\hbar]t} \end{split}$$

where $I_{k_f k}$ is as defined in the assignment and $\delta_{k_f k}$ is the Kronecker delta.

(c) Starting with the initial equation

$$\sum_k c_k(t) I_{k_f k} e^{-i[E(k)/\hbar]t} = i\hbar \frac{\delta c_{k_f}(t)}{\delta t} e^{-i[E(k_f)/\hbar]t}$$

Since we approximated that $c_k = 1$, only when $k = k_i$, and 0 otherwise, we can simplify the sum on the left hand side to a single element, and divide out the exponentials.

$$I_{k_f k_i} e^{i[-E(k_i) + E(k_f)/\hbar]t} = i\hbar \frac{\delta c_k(t)}{\delta t}$$

Defining a new symbol $\Lambda = [E(k_f) - E(k_i)]/\hbar$, we can simplify the equation to it's final form.

$$I_{k_f k_i} e^{i\Lambda t} = i\hbar \frac{\delta c_k(t)}{\delta t} \tag{9}$$

(d)

$$\begin{split} \int \frac{\partial c_{k_f}(t)}{\partial t} &= \frac{1}{i\hbar} I_{k_f k_i} \int e^{i\Lambda t} \\ c_{k_f}(t) &= \frac{1}{i\hbar} I_{k_f k_i} \frac{1}{i\Lambda} e^{i\Lambda t} + C \\ c_{k_f}(t) &= \frac{1}{i\hbar} I_{k_f k_i} e^{i\Lambda t/2} \left[\frac{1}{i\Lambda} e^{i\Lambda t/2} + C e^{-i\Lambda t/2} \right] \end{split}$$

Let $C = -\frac{1}{i\Lambda}$. We then have:

$$\begin{split} c_{k_f}(t) &= \frac{1}{i\hbar} I_{k_f k_i} e^{i\Lambda t/2} \frac{1}{i\Lambda} \left[e^{i\Lambda t/2} - e^{-i\Lambda t/2} \right] \\ c_{k_f}(t) &= \frac{1}{i\hbar} I_{k_f k_i} e^{i\Lambda t/2} \frac{\sin(\Lambda t/2)}{\Lambda/2}. \end{split}$$

(e)